# GRAVITATING LIGHT BALL: STATIONARY STATES AND COLLAPSE DEVELOPING

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ABSTRACT. Equations of motion convenient for numerical solution are deduced within the frame of GR in a spherically symmentic case for a balfilled with light-gas. It is also shown that the variables of the gravitational field can be eliminated from the equations of motion converting the gravitational interaction into the equivalent direct interaction of matter with itself. Stationary states, oscillation modes and instability modes at computed, and processes of decay of "hot" states and collapse are studied.

## INTRODUCTION

The pressure of light grows with temperature as  $T^4$  - faster than the pressure of any massive matter - and is the most important factor of dynamics of the heaviest and hottest celestial objects. So it is reasonable to single out this factor and to analyze the behaviour of the pure light in the gravitational field that it creates In this paper we consider the static distribution and the collapse of the thermal radiation in a large spherical black cavity. If the walls of the cavity are thin an weigh little, it can be viewed as a large balloon filled with light - a light ball.

The static equilibrium of a spherical light ball in the frame of GR was analyze in (Sorkin et al., 1981), where the main attention was paid to the *entropy* of th equilibrium states. It was found that depending on the ratio M/R at the surface of the ball it might have no equilibrium states at all, or have one or more such state corresponding to the local extrema of the entropy. Referring to the theory of state stability (Weinberg, 1972), Sorkin et al. (1981) demonstrated that among the equilibrium states of the light ball only the coolest one is stable.

In the present paper we reproduce in a more direct way some of the results  $\mathfrak o$ 

Sorkin et al. (1981) and go further:

- look for the static solutions that have any mass and surface temperature;
- formulate the spherically symmetric nonstatic problem;
- find spherical instability modes near the equilibrium states;
  - compute the propagation of a local perturbation of unstable static state;
  - demonstrate how an unstable state decays (collapses or anticollapses).

In the static case, the pressure P and the energy density W of the black-body radiation obey the law

$$P=aT^4, W=3P, \tag{1}$$

where

$$a=8\pi^{5}k^{4}/15c^{3}h^{3}=7.5\cdot10^{-15}\text{erg/cm}^{3}\cdot\text{grad}^{4}$$

and T is measured in Kelvin. In the nonstatic case the notion of temperature and the state equation (1) can be used, only if a local thermal equilibrium is reached fast enough compared to the changes of other values. We will suppose that a small amount of dust or other scattering agents are present inside the ball, so the radiation length is small enough, the black-body radiation behaves like a light-gas, and the state equation (1) is always true.

We will consider only spherical configurations of matter and use the standard coordinates

$$g_{\mu\nu} = \text{diag}\{-D(t,r), A(t,r), r^2, r^2 \sin^2\theta\}.$$
 (2)

## **EQUATIONS OF MOTION**

In GR the gravitational interaction of matter obeys the Einstein-Hilbert equations

$$R_{\nu}^{\mu} = -8\pi G T_{\nu}^{\mu},\tag{3}$$

where  $G=6.67\cdot10^{-8}\,\mathrm{cm}^3\mathrm{g}^{-1}\mathrm{s}^{-2}$ , and T is the energy-stress tensor of matter. The Einstein tensor for metric (2) is

$$\tilde{R}_{\nu}^{\mu} = \begin{pmatrix}
\frac{1 - (r/A)'}{r^2} & \frac{\dot{A}}{ADr} & 0 & 0 \\
-\frac{\dot{A}}{A^2r} & \frac{1 - 1/A - rD'/(AD)}{r^2} & 0 & 0 \\
0 & 0 & E_2^2 & 0 \\
0 & 0 & 0 & E_3^3
\end{pmatrix},$$
(4)

where  $A' = \partial A/\partial r$ ,  $\dot{A} = \partial A/\partial t$ , etc., and

$$E_{2}^{2} = E_{3}^{3} = \frac{1}{4} \left( \frac{2\dot{A}}{AD} - \frac{\dot{A}^{2}}{A^{2}D} - \frac{\dot{A}\dot{D}}{AD^{2}} + \frac{A'D'}{A^{2}D} + \frac{2A'}{A^{2}r} - \frac{2D''}{AD} + \frac{D'^{2}}{AD^{2}} - \frac{2D'}{ADr} \right).$$

The stress-energy tensor for the light-gas moving radially with velocity v=th[u(t,r)/2] is

$$T_{\nu}^{\mu} = P \delta_{\nu}^{\mu} + (W+P) U^{\mu} U_{\nu}$$

where  $U_{\mu} = \{-ch(u/2)\sqrt{D}, sh(u/2)\sqrt{A}, 0, 0\}$ , so

$$T_{\nu}^{\mu} = P \begin{pmatrix} -2 \operatorname{ch} u - 1 & +2 \sqrt{A/D} \operatorname{sh} u & 0 & 0 \\ -2 \sqrt{D/A} \operatorname{sh} u & 2 \operatorname{ch} u - 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}. \tag{5}$$

Equation (4) gives 4 independent equations

$$\frac{1 - (r/A)'}{r^2} = p(2chu + 1), \tag{6.1}$$

$$\frac{\dot{A}}{ADr} = -2p\sqrt{A/D} \text{shu} , \qquad (6.2)$$

$$\frac{1-1/A-rD'/(AD)}{r^2} = -p(2chu-1), \tag{6.3}$$

$$E_2^2 = -p,$$
 (6.4)

where  $p=8\pi GP$ , for 4 unknown functions A(t,r), D(t,r), p(t,r), u(t,r). This system is rather messy, especially the latter equation, containing A,D''. An equivalent, but more clear system can be obtained, if equations (6.2), (6.4) are replaced by the linear combinations of all equations (6) - by the covariant divergences of both sides of (4):

$$R_{\mathbf{t}:\mu}^{\mu} = -8\pi G T_{\mathbf{t}:\mu}^{\mu}, \qquad R_{\mathbf{r};\mu}^{\mu} = -8\pi G T_{\mathbf{r};\mu}^{\mu}.$$

Due to the Bianci identities, the left-hand sides of these equations vanish, and we have two equations

$$T^{\mu}_{t:\mu} = 0, \quad T^{\mu}_{r:\mu} = 0,$$
 (7)

containing  $\dot{p}$ ,  $\dot{u}$ . Solving system (7) for  $\dot{p}$ ,  $\dot{u}$  and using equation

$$\dot{A}=-2\sqrt{A/DADrpshu}$$
, (6.2a)

(stemming from (6.2)) to exclude  $\dot{A}$ , we obtain

$$\dot{p} = \sqrt{\frac{D}{A}} \frac{1}{2 + \text{ch}u} \left\{ -p' \text{ sh}u + p \left[ 4 \text{sh}u \left( Apr \frac{1}{r} - \right) - 2u' \right] \right\} , \qquad (8.1)$$

$$\dot{u} = -\sqrt{\frac{D}{A}} \left( \frac{D'}{D} + \frac{\frac{3p'}{2p} + 2\frac{1-\text{ch}u}{r} + u' \text{sh}u - 2Apr \text{sh}^2 u}{2 + \text{ch}u} \right). \tag{8.2}$$

These equations combined with equations (6) can be rewritten as

$$\frac{A'}{A} = -\frac{A-1}{r} + Apr(2chu+1), \tag{9.1}$$

$$\frac{D'}{D} = \frac{A-1}{r} + Apr(2chu-1), \tag{9.2}$$

make 4 first-order partial derivative equations suitable for analysis and numeric solution.

The systems (8), (9) are rather curious. The functions p,u describing the state of the matter play there a more fundamental role than the metric elements D,A. From the mathematical point of view, the knowledge of functions  $p(t_0,r)$ ,  $u(t_0,r)$  is sufficient for the computation of  $D(t_0,r)$ ,  $A(t_0,r)$ ,  $\dot{p}(t_0,r)$ ,  $\dot{u}(t_0,r)$ , and completely defines the evolution of matter.

Indeed, using  $p(t_0,r)$ ,  $u(t_0,r)$  (and the regularity condition A(t,0)=1) we can solve (9.1) and find  $A(t_0,r)$ , then solve (9.2) and find  $D(t_0,r)$  (the unessential normalization factor can be set by the relation

$$D(t_0, r_3) = 1/A(t_0, r_3)$$

on the surface of the ball). After that  $\dot{p}$ ,  $\dot{u}$  at  $t=t_0$  are immediately computable.

From the physical point of view, the entities D, A, since they do not enter initial conditions, are *auxiliary* functions and can be excluded from the equations of matter evolution.

Indeed, defining a running mass M(t,r) by the relation

$$A = 1/(1-M/r), \tag{10}$$

we can cast (9.1) to the form

$$M' = pr^2(2chu+1),$$
 (11)

whence

$$M = \int_{0}^{r} p(2\operatorname{ch}u+1)r^{2}dr. \tag{12}$$

Equation (9.2) gives

$$D = \operatorname{const} \cdot \exp \left\{ \int_{0}^{r} \left[ \frac{A-1}{r} + \operatorname{Apr}(2\operatorname{chu}-1) \right] dr \right\}.$$
 (13)

Substitution of (10), (12), (13) into (8) transforms it into a set of tegroin differential equations for functions p, u only, describing the evolution of matter interacting directly with itself.

Equations (9) are curious in one more aspect. According to (9), an abrupt local perturbation of p(t,r) near some point  $r_0$  leads, formally, to the instant change of p(t,r) near some point p(t,r) leads, formally, to the instant change of p(t,r) near some point p(t,r) which seems to violate the causality principle p(t,r) actually, the causality principle is not violated for two reasons. One of them is that equation (6.2) (which is always valid) clearly tells that p(t,r) are changes of p(t,r) only locally. Another reason is that according to (9.2) after the perturbation only the normalizations of p(t,r) within each region p(t,r) and p(t,r) are changed, and this effect cannot be noticed instantly: to measure the change in the ratio of the normalizations in the two regions, one has to wait for the arrival of a light signal from the other region. So, no signal moving faster than light can be transferred due to equations (9).

## STATIONARY STATES

In the static case  $\dot{p}=\dot{u}=u=0$ , equation (8.1) becomes trivial and other equation reduce to

$$\frac{D'}{D} = -\frac{p'}{2p'},\tag{14}$$

$$\frac{A'}{A} = -\frac{A-1}{r} + 3Apr, \tag{15}$$

$$\frac{D'}{D} = \frac{A-1}{r} + Apr. \tag{16}$$

Equation (14) says that  $p\sim 1/D^2$  and, together with (1), that  $T^2\sim 1/D$ . It is just particular case of the well-known fact that the equilibrium temperature in the gravitational field is not constant. Instead, the *visible* temperature at point observed from point x does not depend on y

$$T(y;x)=T(y)\sqrt{g_{00}(y)/g_{00}(x)} = T(x).$$

If the observation point x is inside the light ball and the observed point y is a

its surface, the factor

$$\sqrt{g_{00}(y)/g_{00}(x)} > 1$$

and is a *blue* shift, due to which the temperature near the center of the light ball should be higher than at the surface. Substituting  $p(r)=p_0D(0)^2/D(r)^2$ , where  $p_c=p(0)$  is the pressure at the center, and using instead of D, A the functions

$$B(r) = M(r)/r = 1-1/A,$$
  $f(r) = D(0)^2/D(r)^2,$ 

we rewrite (15), (16) as

$$B' = 3p_{c}rf - B/r,$$

$$f'/2f = -(B/r + p_{c}rf)/(1-B).$$
(17)

Since  $f(0)\equiv 1$  and B(0)=0, the boundary conditions in (17) at r=0 are completely fixed. The system (17) has an exceptional solution

$$B_{e} = 3/7, \qquad f_{e} = 7p_{c}/r^{2}$$
 (18)

that does not satisfy the condition f(0)=1. As we shall soon see, every solution B(r) of (17) tends to  $B_e$  at  $r\to\infty$ , so  $B_e$  is an attractor.

Since photons are massless and the boundary conditions at the center do not contain any scale, equations (17) should be scale-invariant. Indeed, if  $\{B(r), f(r)\}$  is the solution of (17), the couple of functions

$$\tilde{B}(r) = B(r\lambda), \quad \tilde{f}(r) = f(r,\lambda)$$

is the solution of (7) for the same initial conditions at r=0 and for  $p_c$  replaced by  $\tilde{p}_c = p_c \lambda$ . Therefore, it is sufficient to know the function  $B_*(r)$  satisfying the parameter-free equations

$$B'_{*} = 3rf_{1} - B_{*}/r, \qquad f'/2f = -(B_{*}/r + rf)/(1-B_{*})$$
 (19)

with the conditions  $B_*(0) = 0$ , f(0) = 1: solution B(r) of (17) for any  $p_c$  can be obtained from  $B_*(r)$  with a scale transformation.

The functions  $B_*$ , f are easily computed numerically. The behaviour of f is better seen, if one plots  $F=3r^2f$  instead of f (see Fig. 1)

The function  $B_*(r)$  starts to increase parabolically from zero, reaches at r=1.92 the maximum  $B_{\rm max}=0.493$ , then slowly decreases and reaches at r=11.6 the first minimum  $B_{\rm min}=0.411$ , and then slowly oscillating tends to the asymptotic value  $B_*=3/7$ . At large r=1.92

$$B_{*} \approx ar^{-3/4} \cos(\omega \ln(r/r_a)) + 3/7,$$
 (20)

where  $a\approx 0.119$ ,  $\omega\approx (47/16)^{1/2}$ , and  $r_{\rm a}\approx 1482$ . The function F due to relation  $F=B_*+r$  has a similar asymptotic.

The solution B(r), f(r) for the given  $p = T(0)^4 a 8\pi G$  is

$$B(r) = B_1(r\lambda), \qquad f(r) = f_1(r\lambda), \qquad \lambda = \sqrt{p_c}. \tag{21}$$

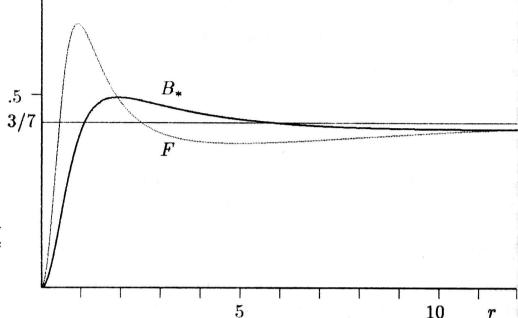


Fig. 1. Basic solution of static equation.

At large  $r_0$  and r every solution tends to the exceptional one, so it is an attractory. The exceptional solution  $B_e$  can be also considered as an improper limit of B at  $p \not \sim$  Let us return to the physically more interesting functions D(r),  $p(r) = p_c f(r)$ . If find D, one has to fix the radius  $r_3$  of the ball. Since outside the ball there is no matter and the Schwarzshild solution is true, we should have at the surface  $D(r_3) = \frac{1}{2} (r_3)$ . Hence,

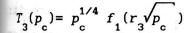
$$D(r) = [1 - B(r_3)] \sqrt{f(r_3)/f(r)}$$

The curves B,D and  $T=0.5 \cdot p^{1/4}$  for two states with the same mass and radius (M=0.4  $r_3$ =1) are given in Fig. 2. The temperature at the center for the hot solution is three times larger than for the cool one.

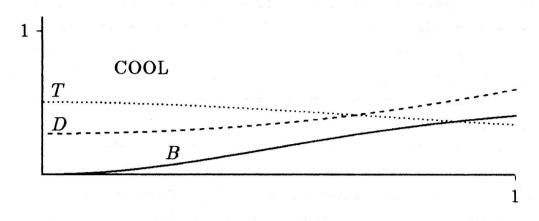
## STATIONARY SOLUTIONS CONTINUED FROM THE SURFACE

In case of cosmic objects observed from outside, it is more natural to use as known parameter not the temperature at the center, but rather the total mass  $M_{\infty} = M(n_0)$  and the temperature  $T_{3} = T(r_{3})$  at the surface of the body. Due to the regularity condition B(0)=0, the only free parameter is  $T(0)\sim p_{0}^{1/4}$  and the values

$$B_3(p_c) = B_1(r_3\sqrt{p_c}),$$



make a 1-parameter family (see the spiral-like curve in Sorkin et al., 1981). The natural question arises which solution of equations (15),(16) correspond to  $M_{\infty}$  and  $T_{3}$  not belonging to this family.



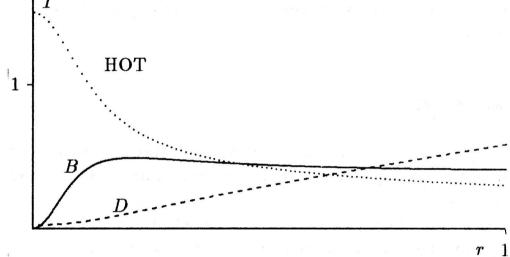
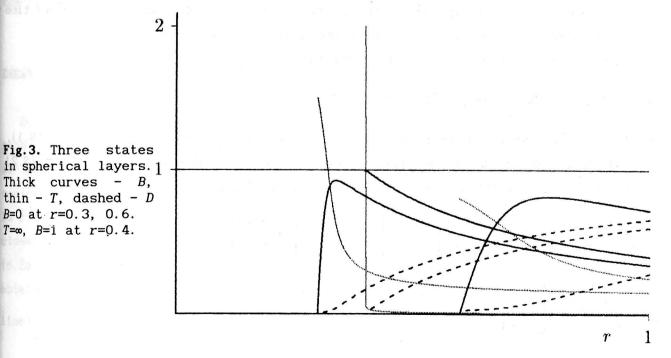


Fig. 2. Two states with the same mass and radius.

Three typical solutions of (15), (16) are drawn in Fig. 3.



The solutions continued from the surface toward the center generally do not reach it at some point  $r_*$  either the mass M(r) (and function B(r)) becomes zero, or function B(r) reaches 1 and the temperature  $T(r) = T_3 \sqrt{D(r_3)/D(r)}$  becomes infinite. Such solutions describe the static distribution of the black-body radiation not in the globe but in the spherical layers enclosed between two hard spheres of radii  $r_i > r_*$  and  $r_3$ . The value  $M_i = B(r_i)r_i$  is the mass of the inner sphere and  $T(r_i)$  is the temperature of its surface. If  $B(r_i)$  is close to 1, the radiation is condensed in a thin layer of the inner sphere, like an ocean on the surface of the Earth. To prevent the radiation from falling toward the center, the inner sphere should be hard enough to resist its pressure.

Now we are able to answer the question what happens in the original model (where the internal sphere is absent) if one pumps into the cavity too much radiation, so the ratio B=M/r will exceed the limit  $B_{\max}$ . Since we know all the static solution and among them there is none (neither regular, nor singular) with such B, the 'overdosed' radiation will never reach thermal equilibrium; the state will never become static.

## UNSTABLE STATES

If  $M_{\infty}$  and  $r_3$  of the light ball (here and below - without the internal sphere) are fixed and  $B_{\min} < b < B_{\max}$ , there are several solutions of B(r) describing different physical states of the light ball with the same mass  $M_{\infty}$  (see Fig.2). As was pointed in (Sorkin et al., 1981), among these states only the coolest one (which is described by a monotonically increasing part of B(r)) is stable. The unstable states decay: the long-wave component of a small perturbation grows exponentially with time as  $e^{t/\bar{t}}$ . If the early stage of the decay, while the perturbation is still small, the decay time and the shape of decay harmonics can be found like the small oscillations.

Let the state be close to the static solution  $p_0$ ,  $p_0$ ,  $A_0$ :

$$p=p_0 + \delta p$$
,  $u=\delta u$ ,  $D=D_0 + \delta D$ ,  $A=A_0 + \delta A$ ,

where  $\delta p$ ,... and their derivatives  $\delta p$ ,  $\delta p'$ ,... are small. Substituting this in (8.1) (8.2), (6.2a), keeping only the terms linear in  $\delta p$ ,..., and excluding D'/D in (8.2) by means of (9.2), we obtain the system of three equations

D

$$\delta \dot{u} = -\sqrt{\frac{D_0}{A_0}} \left[ \delta A \left( p_0 r + \frac{1}{r} \right) + \delta p \left( A_0 r - \frac{p_0'}{2p_0^2} \right) + \frac{\delta p'}{2p_0} \right],$$

$$\delta \dot{p} = \sqrt{\frac{p_0}{A_0}} \frac{p_0}{3} \left[ \delta u \left[ 4A_0 p_0 r - \frac{4}{r} - \frac{p_0'}{p_0} \right] - 2\delta u' \right],$$

$$\delta \dot{A} = -2\delta u D_0 A_0 p_0 r \sqrt{A_0/D_0}.$$

Seeking oscillation solutions

$$\delta u = \bar{u}(r)\cos\omega t$$
,  $\delta p = \bar{p}(r)\frac{\sin\omega t}{\omega}$ ,  $\delta A = \bar{A}(r)\frac{\sin\omega t}{\omega}$ ,

expressing  $p_0'$  through  $A_0$ ,  $p_0$  with the help of (14), (16), and excluding  $\bar{A}$  from the equations for  $\dot{u},\dot{p}$ , we finally obtain

$$\bar{u}' = \bar{u} \left( \frac{A_0^{-3}}{r} + 3A_0 p_0 r \right) - \bar{p} \frac{3}{2p_0} \sqrt{\frac{A_0}{D_0}},$$

$$\bar{p}' = 2\bar{u}p_0 \sqrt{\frac{A_0}{D_0}} \left[ \omega^2 + 2p_0 A_0 D_0 (p_0 r^2 + 1) \right] - 2\bar{p} \left( \frac{A_0^{-1}}{r} + 2A_0 p_0 r \right).$$
(22)

The regularity conditions in the center are:

$$\bar{u}(0) = \bar{p}'(0) = 0.$$

The boundary (normalization) condition is  $\bar{p}'(0)$ =const. In case of instability modes  $\omega$  becomes imaginary, but equations (22) do not change: only parameter  $\omega^2$  becomes negative.

Fig. 4 shows the curves p(r), u(r) for several values of  $\omega^2$ .

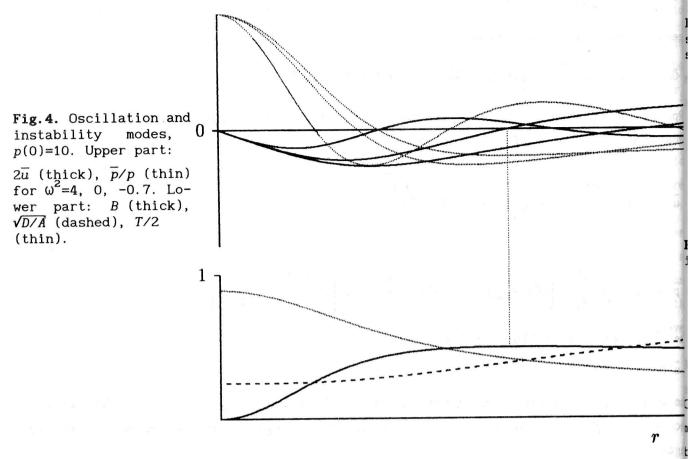
Clearly, if  $\omega=0$ , the knot of the function  $\bar{u}(r)$  coincides with the point of maximal B(r).

The proper values  $\omega_n^2$  are fixed by the condition  $u(r_3)$ . The oscillation mode with negative  $\omega^2$  exists only if the globe radius  $r_3$  is greater or equal to the point  $r_u$ , where u changes sign. One can also see that up to  $r_3$  rather large compared to  $r_u$  only one instability mode (mode with  $\omega^2 < 0$ ) exists.

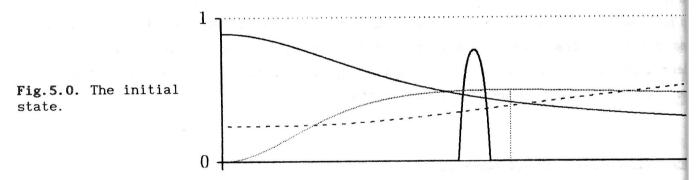
## DECAY AND COLLAPSE OF UNSTABLE STATE

Due to the nonlinearity of the equations of motion, any perturbation of an unstable state excites the instability mode and this mode starts to grow exponentially as  $\sinh|\omega t|$ . Depending on the sign of excitation, the state may evolve toward the cooler state, or evolve toward the hotter state and pass into collapse. The process is rich in details that are not easy to predict from general consideration. To have a closer look at the evolution of the light ball, the system of equations (8.1), (8.2), (6.2a), (9.2) was solved numerically with a number of initial states. One of the obtained movies is represented by a series of Figs. 5.0-5.9, where v=thu/2 (solid line),  $T=0.5 \cdot p^{1/4}$  (thin line), B=M/r (dotted line),  $\sqrt{D}$  (dashed line), and  $r_3=1$ . The

dotted vertical line indicated the maximum of B.



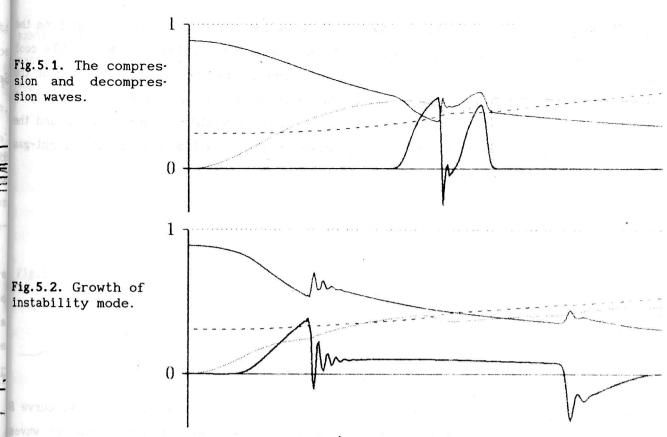
The initial state (Fig. 5.0, t=0) is an unstable stationary state locally perturbed by pushing a layer of light-gas toward the surface (v>0).



Soon (Fig. 5.1, t=0.2) this push turns into two localized waves: compression wave moving toward the surface and decompression wave moving toward the center.

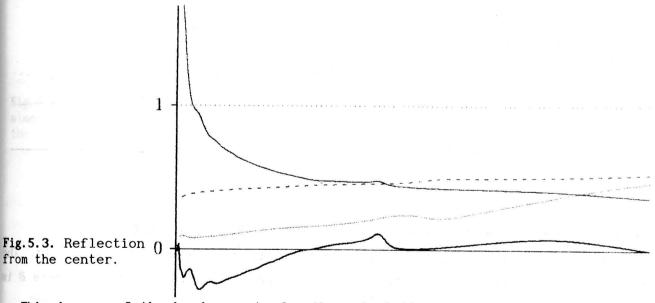
Since the push was strong - the initial velocity was greater than the velocity of sound =  $1/\sqrt{3}$  - both waves have steep shock fronts and are followed with tails of small oscillations. At t=1 the right wave is already reflected from the surface while the other wave is still approaching the center since, due to the factor  $\sqrt{D}/\sqrt{10}$  in (8), the speeds of light and of sound are smaller in the central region than near the surface.

At t=2.6 (Fig. 5.2), the growth of the instability mode becomes well pronounced.



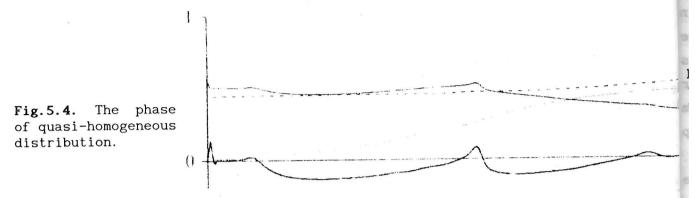
Of course, the initial perturbation, due to nonlinearity of the equations, excites many other oscillation modes, but they stay small and invisible, and only the instability mode shows up.

Next slide (Fig. 5.3) at t=3.9 shows a high peak of pressure, when the left wave is reflected from the center and turns into a number of waves.

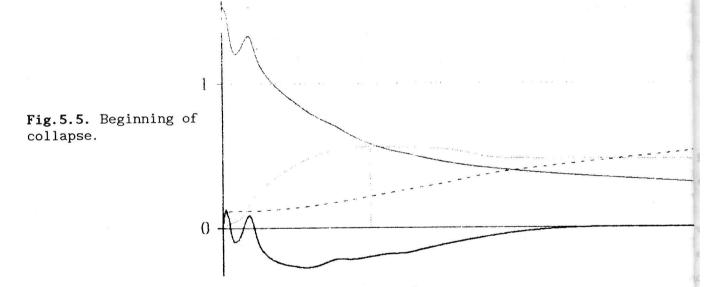


This is one of the hard moments for the calculation procedure since, besides the growth of wave amplitude, the finiteness of step  $\Delta r$  (this movie was produced with  $\Delta r = r_3/300$ ) excites the noise ultrasound waves concentrating near the center. To get a clean picture, one has to damp these ultrasound waves, which is done with the help of some smoothing local averaging of p and u equivalent to the admission of nonzero

At t=5 (Fig. 5.4), the instability wave stops growing and starts reflecting from the surface. The state of the light ball at this moment is similar to the stable constate in Fig. 2. The stopping of the instability wave is an unrealistic feature of the model: in case of a star such a wave would cause an explosion and a shake-off of particle of the mass. But here, since the light-gas is contained within a hard sphere and the shake-off is impossible, the instability wave is reflected and soon the light-gas starts moving toward the center.



At t=9.8 (Fig. 5.5), the early stage of collapse is seen. The hump on the curve is forming. The speed of falling light-gas is about the speed of sound, so the wave from the center hardly move and gradually fade.

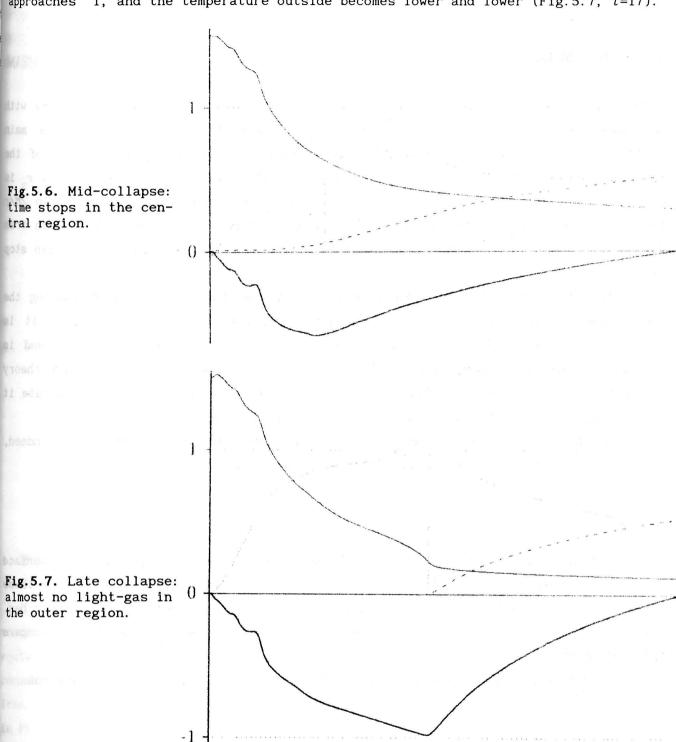


At t=10.9 (Fig. 5.6), the collapse is well-developed,  $B_{max}$  is about 0.77.

The speed of falling light-gas now reaches half of the velocity of light. The motion of waves in the internal region (to the left of the 'bottle-neck', where B is maximal) is practically stopped ( $\sqrt{D/A} \sim 0$ ). This picture later does not change except that the light-gas in the external region is constantly sucked inside,  $B_{\rm max}$  approaches 1, and the temperature outside becomes lower and lower (Fig. 5.7, t=17).

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maximal) is practically stopped ( $\sqrt{D/A} \sim 0$ ). This picture later does not change, except that the light-gas in the external region is constantly sucked inside,  $B_{\text{max}}$  approaches 1, and the temperature outside becomes lower and lower (Fig. 5.7, t=17).



The model of ball with hard walls is rather unrealistic, so it is interesting to know what will happen in case of open light ball, having no walls. The calculation of evolution in an unlimited region of space needs a more complicated program, so as to obtain a preliminary picture of collapse of wallless ball, we imitated the absence of walls by changing the boundary conditions at the surface: we set u'=0 instead of u=0, thus letting the light-gas leave the sphere  $r\leqslant 1$ . We took the state of

mid-collase as an initial state and repeated calculations. Without walls, the evolution was similar to that of a walled ball, only part of the light-gas near the boundary, was going off.

## CONCLUDING REMARKS

The static and dynamical properties of the light ball are mainly in harmony with what was expected from crude estimates and general considerations. The main difference of the light-gas from the heavy matter is that the stable state of the light ball (the coolest solution) may have arbitrary large mass if the radius  $r_3$  large enough (only the ratio M/r is limited by  $B_{\rm max}/2$ ). However, if the ratio 2M/r somewhere exceeds  $B_{\rm max}$ , the light ball collapses, turning into an object seen from outside as a dark ball of standard radius  $r\sim 2M$ . In the frame of GR, nothing can state collapse.

A self-graviting light ball is a good object for the purpose of comparing the predictions of GR with predictions of other gravitational theories since it is sensitive to the relativistic and nonlinear terms in equations of motion and is reasonably easy to analyze numerically even in the nonstatic case. If a new theory claims to stop collapse of a heavy star, it should first be able to demonstrate if for the light ball. Same can be said for the supposed rebounce.

A light ball may be considered as a crude approximation of a quark star. Indeed the matter in the quark star models is usually supposed to obey the law

$$P = \frac{1}{3} \bigg[ W - 4b \bigg],$$

where b is a bounding energy density of the quark plasma. Except for the surfact layer, where W~4b, the properties of quark matter inside the star are close to those of the light-gas, so the quark star may be viewed as a light ball in an elastic bag It would be interesting to calculate the oscillation modes of quark stars and company them with those of the light ball.

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